

Deterministic Algorithms for the Lovász Local Lemma¹

Jonas Hübotter and Duri Janett
Advised by Yassir Akram

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¹David G Harris. “Deterministic algorithms for the Lovász local lemma: simpler, more general, and more parallel”. In: *Proceedings of the 2022 Annual ACM-SIAM Symposium on Discrete Algorithms (SODA)*. SIAM. 2022, pp. 1744–1779.

Setting

Distribution D over independent Σ -valued coordinates X_1, \dots, X_n .
“Bad-events” $\mathcal{B} = \{B_1, \dots, B_m\}$, each a boolean function of some subset of coordinates $\text{var}(B_i) \subseteq \{X_1, \dots, X_n\}$ with law p .

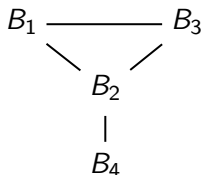
Example (3-SAT)

$$B_1 \doteq f_1(X_1, X_3, X_5)$$

$$B_2 \doteq f_2(X_2, X_3, X_6)$$

$$B_3 \doteq f_3(X_1, X_5, X_6)$$

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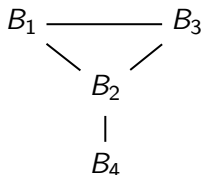
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Theorem ((Symmetric) Lovász Local Lemma)

If for any i , $p(B_i) \leq p_{\max}$ and B_i affects at most d bad-events, then $ep_{\max}d \leq 1$ implies $\Pr[\text{all } B_i \text{ avoided}] > 0$.

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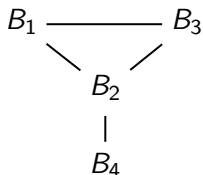
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For k -SAT and $X_i \sim \text{Unif}(\{0, 1\})$, $p \equiv 2^{-k}$.

\rightsquigarrow satisfiable if any variable appears in at most $2^k/k_e$ clauses!

Applications

Example (k-Coloring)

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$$p(B_{v,c}) = \frac{1}{k} \left(\sum_{u \in N(v)} \frac{1}{k} \right) \leq \frac{\Delta}{k^2}$$

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More applications:

1. Defective coloring
2. Hypergraph coloring
3. Strong coloring
4. Non-repetitive coloring
5. Finding directed cycles of certain length (see exam, task 2 :))
6. Independent transversals

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\rightsquigarrow algorithmic versions of the Lovász Local Lemma yield automatic algorithms for these problems!

Prior Work

Algorithm: MT-Algorithm

Draw X from distribution D

while *some bad-event is true on X* **do**

 | Select any true bad-event B

 | For each $i \in \text{var}(B)$, draw X_i from its distribution in D

end

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\rightsquigarrow converges within expected polynomial time.²

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Prior Work

Paper	Criterion	Det.?	Parallel?
3	asymmetric LLL	✗	(✓)
3	asymmetric LLL and $d \leq \mathcal{O}(1)$	✓	(✓)
4	symmetric LLL with ϵ -exponential slack	✓	(✓)
5	Shearer criterion with ϵ -slack	✗	✓
5	symmetric LLL with ϵ -exponential slack and atomic bad-events	✓	✓
6	symmetric LLL and bad-events depend on $\text{polylog}(n)$ variables	✓	✓

(✓) : under more complex conditions

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⁴Karthekeyan Chandrasekaran, Navin Goyal, and Bernhard Haeupler. "Deterministic algorithms for the Lovász local lemma". In: *SIAM Journal on Computing* 42.6 (2013), pp. 2132–2155.

⁵Bernhard Haeupler and David G Harris. "Parallel algorithms and concentration bounds for the Lovász local lemma via witness-DAGs". In: *Proceedings of the Twenty-Eighth Annual ACM-SIAM Symposium on Discrete Algorithms*. SIAM. 2017, pp. 1170–1187.

⁶David G Harris. "Deterministic parallel algorithms for fooling polylogarithmic juntas and the Lovász local lemma". In: *ACM Transactions on Algorithms (TALG)* 14.4 (2018), pp. 1–24.

Contributions

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2. Faster *parallel algorithm* with simpler conditions.
3. We can ensure that the final distribution of the deterministic algorithm is not “far off” from the distribution at the end of the MT algorithm.

Plan

Introduction

Background

- Alternative Characterization of MT Algorithm

- Counting Resamples

- Analyzing the MT Algorithm

A Deterministic Algorithm

Alternative Characterization of MT Algorithm

Consider the **resampling table** R drawn according to distribution D :

	1	...	t	...
X_1	*	*	*	...
\vdots	\vdots	\vdots	\vdots	...
X_n	*	*	*	...

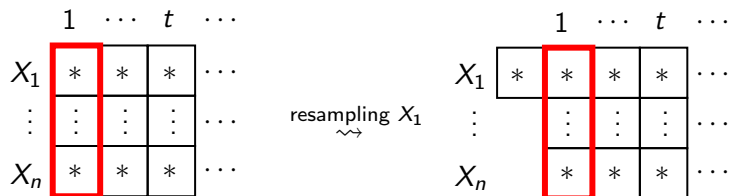
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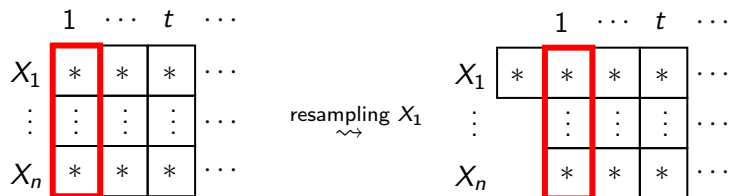
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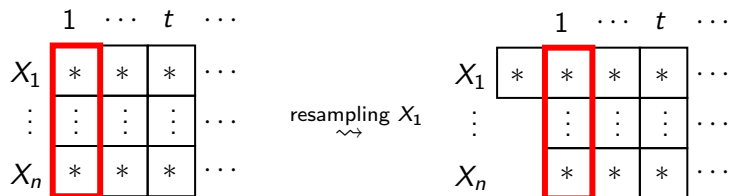
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When resampling B_i , shift rows $\text{var}(B_i)$ to left.

\rightsquigarrow MT algorithm deterministic with respect to resampling table!

Counting Resamples

Want to find an encoding of resamples such that we do not lose much information.

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Why may executions be long?

Given a resampling table R , a (partial) execution of the MT algorithm is described by the sequence of resampled bad-events.

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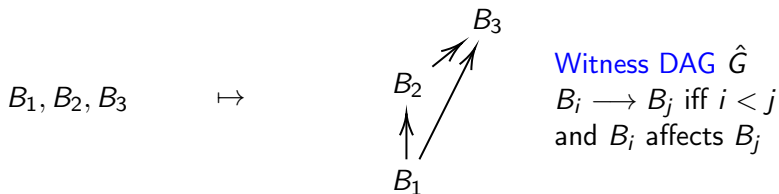
$B_1, B_2, B_3 \quad \mapsto$

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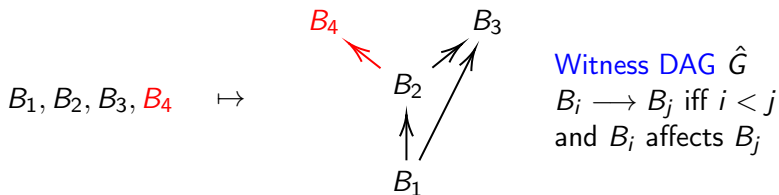


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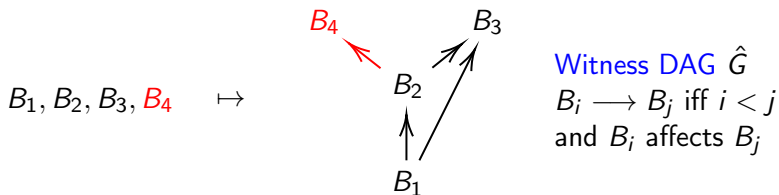


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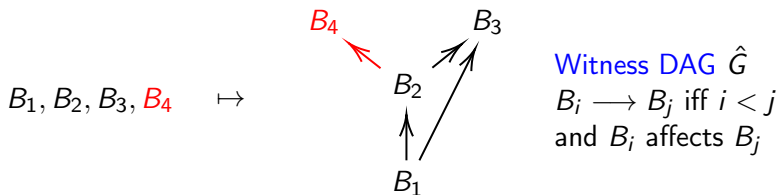
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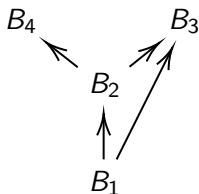
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$\rightsquigarrow \hat{G}$ is always a DAG! But why are DAGs a good encoding?

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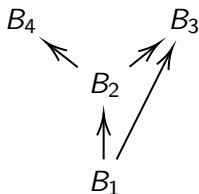
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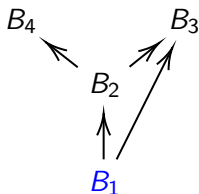
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*	*	*	...	X_2
*	*	*	...	X_3
*	*	*	...	X_4
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fixed resampling table R

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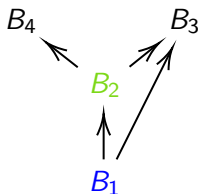
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resamples: B_1

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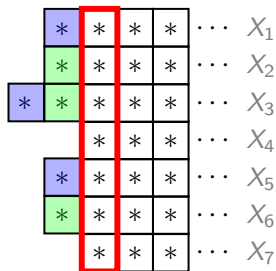


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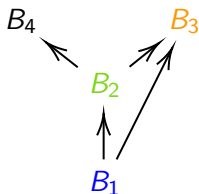
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fixed resampling table R
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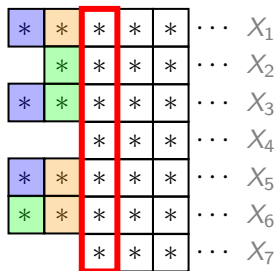


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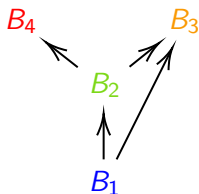
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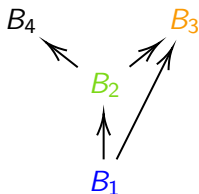
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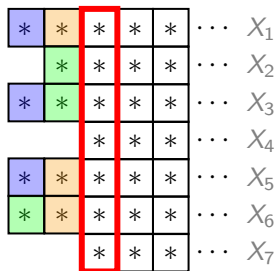


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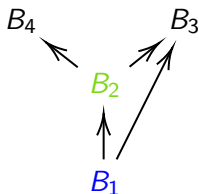
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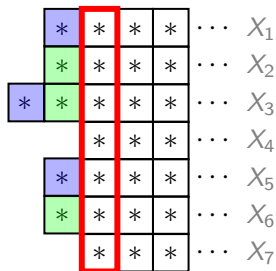


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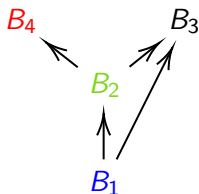
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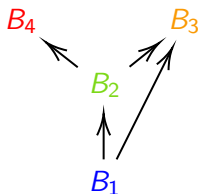
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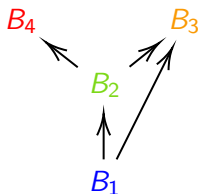
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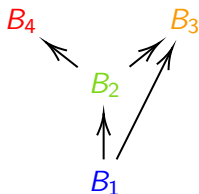
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\rightsquigarrow may encode multiple executions, but *all* lead to the same final configuration!

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*	*	*	*	*	...	X_1
*	*	*	*	*	...	X_2
*	*	*	*	*	...	X_3
	*	*	*	*	...	X_4
*	*	*	*	*	...	X_5
*	*	*	*	*	...	X_6
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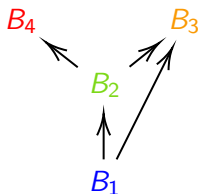
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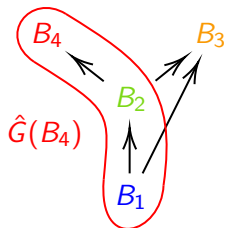
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Plan

Introduction

Background

A Deterministic Algorithm

- Likely & Unlikely Resamples

- The Algorithm

- Limitations

Likely & Unlikely Resamples

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Example $w_p(G) = 1/4$. $B_1 \rightarrow B_2$

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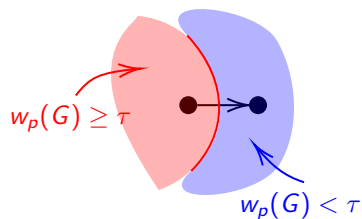
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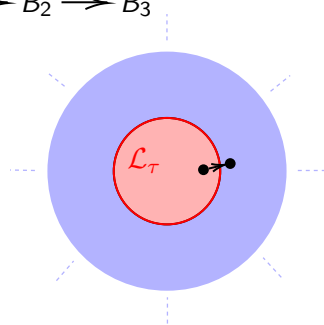
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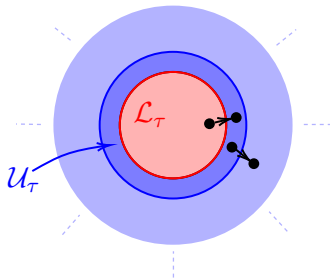
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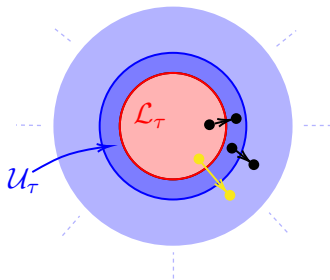
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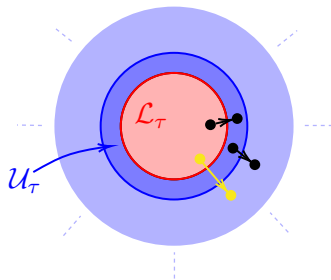
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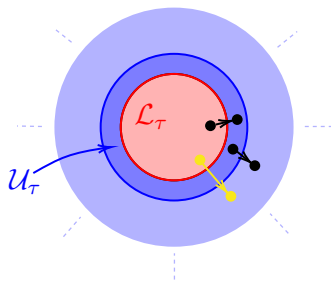
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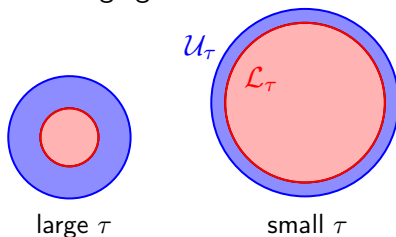
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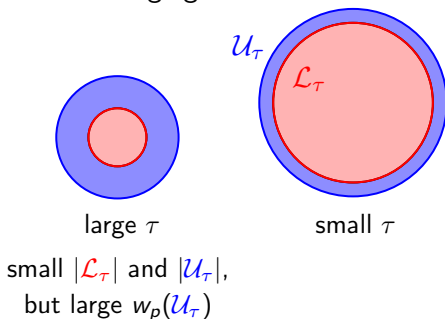
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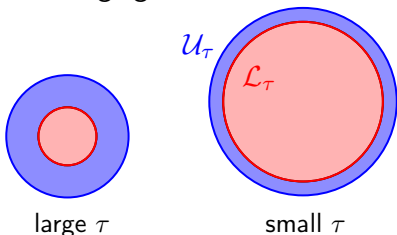
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small $|\mathcal{L}_\tau|$ and $|\mathcal{U}_\tau|$, but large $w_p(\mathcal{U}_\tau)$ large $|\mathcal{L}_\tau|$ and $|\mathcal{U}_\tau|$,
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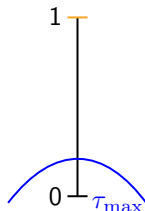
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Use exponential backoff!

Example $\tau = 2^0 = 1$.



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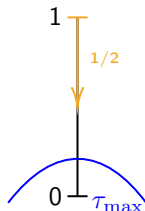
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Example $\tau = 2^{-1} = 1/2$.



Choosing the Threshold

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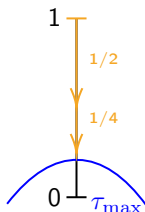
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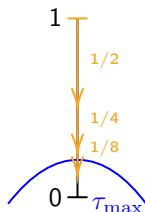
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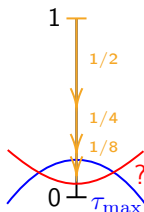
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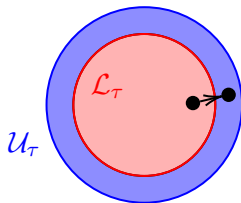
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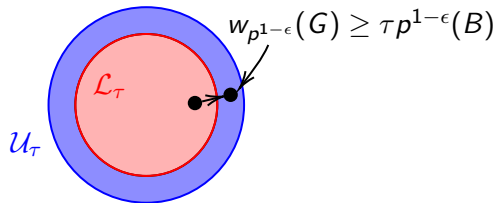
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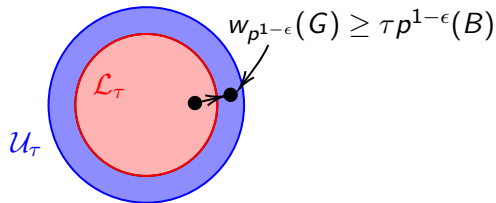
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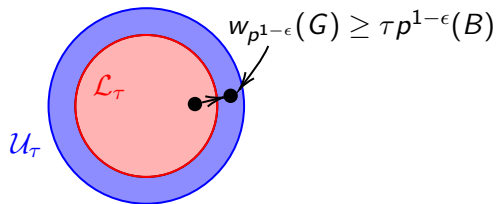
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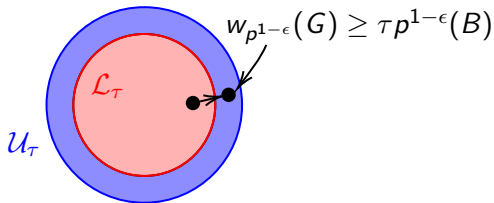


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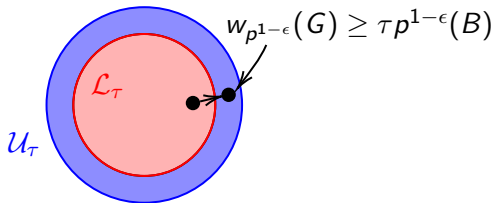
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W_ϵ is polynomial under common LLL conditions!

The Algorithm

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Using exponential backoff, select “large” τ such that $w_p(\mathcal{U}_\tau) < 1$

Using method of conditional expectations, find resampling table R avoiding \mathcal{U}_τ

Run the deterministic MT algorithm on R

We have seen that the final step takes at most $|\mathcal{G}[R]| \leq |\mathcal{L}_\tau[R]|$ iterations!

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Thanks for your attention! Questions?

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Also need to generate \mathcal{U}_T , which can be done in $\text{poly}(|\mathcal{U}_T|)$ time.

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$$\begin{aligned} \sum_{J \subseteq \bar{\Gamma}(B)} \prod_{B' \in J} ep(B') &\leq \sum_{J \subseteq \bar{\Gamma}(B)} (ep_{\max})^{|J|} \leq \sum_{k=0}^d \binom{d}{k} (ep_{\max})^k \\ &= (1 + ep_{\max})^d \leq \exp(\underbrace{ep_{\max} d}_{\leq 1}) \leq e. \end{aligned}$$